

Output Analysis and Run-Length Control

In these notes we describe how the Central Limit Theorem can be used to construct approximate $(1 - \alpha)\%$ confidence intervals for the quantity, θ , we are trying to estimate. We also describe methods to estimate the number of samples that are required to achieve a given confidence level and we end with a discussion of the bootstrap method for performing output analysis.

1 Output Analysis

Recall the simulation framework that we use when we want to estimate $\theta := \mathbb{E}[h(\mathbf{X})]$ where $\mathbf{X} \in \mathbb{R}^n$. We first simulate $\mathbf{X}_1, \dots, \mathbf{X}_n$ IID and then set

$$\hat{\theta}_n = \frac{h(\mathbf{X}_1) + \dots + h(\mathbf{X}_n)}{n}$$

The Strong Law of Large Numbers (SLLN) then implies

$$\hat{\theta}_n \rightarrow \theta \text{ as } n \rightarrow \infty \text{ w.p. } 1.$$

But at this point we don't know how large n should be so that we can have confidence in $\hat{\theta}_n$ as an estimator of θ . Put another way, for a fixed value of n , what can we say about the quality of $\hat{\theta}_n$? We will now answer this question and to simplify our notation we will take $Y_i := h(\mathbf{X}_i)$.

1.1 Confidence Intervals

One way to answer this question is to use a *confidence interval*. Suppose then that we want to estimate θ and we have a random vector $\mathbf{Y} = (Y_1, \dots, Y_n)$ whose distribution depends on θ . Then we seek $L(\mathbf{Y})$ and $U(\mathbf{Y})$ such that

$$\mathbf{P}(L(\mathbf{Y}) \leq \theta \leq U(\mathbf{Y})) = 1 - \alpha$$

where $0 \leq \alpha \leq 1$ is a pre-specified number. We then say that $[L(\mathbf{Y}), U(\mathbf{Y})]$ is a $100(1 - \alpha)\%$ confidence interval for θ . Note that $[L(\mathbf{Y}), U(\mathbf{Y})]$ is a random interval. However, once we replace \mathbf{Y} with a sample vector, \mathbf{y} , then $[L(\mathbf{y}), U(\mathbf{y})]$ becomes a real interval. We now discuss the Chebyshev Inequality and the Central Limit Theorem, both of which can be used to construct confidence intervals.

The Chebyshev Inequality

Since the Y_i 's are assumed to be IID we know the variance of $\hat{\theta}_n$ is given by $\text{Var}(\hat{\theta}_n) = \frac{\sigma^2}{n}$ where $\sigma^2 := \text{Var}(Y)$. Clearly a small value of $\text{Var}(\hat{\theta}_n)$ implies a more accurate estimate of θ and this is indeed confirmed by *Chebyshev's Inequality* which for any $k > 0$ states that

$$\mathbf{P}\left(|\hat{\theta}_n - \theta| \geq k\right) \leq \frac{\text{Var}(\hat{\theta}_n)}{k^2}. \tag{1}$$

We can see from (1) that a smaller value of $\text{Var}(\hat{\theta}_n)$ therefore improves our confidence in $\hat{\theta}_n$. We could easily use Chebyshev's Inequality to construct (how?) confidence intervals for θ but it is generally very conservative.

Exercise 1 Why does Chebyshev's Inequality generally lead to conservative confidence intervals?

Instead, we will use the Central Limit Theorem to obtain better estimates of $\mathbf{P}\left(|\hat{\theta}_n - \theta| \geq k\right)$ and as a result, narrower confidence intervals for θ .

The Central Limit Theorem

The Central Limit Theorem is among the most important theorems in probability theory and we state it here for convenience with the symbol " \xrightarrow{d} " denoting convergence in distribution.

Theorem 1 (Central Limit Theorem)

Suppose Y_1, \dots, Y_n are IID and $\mathbb{E}[Y_i^2] < \infty$. Then

$$\frac{\hat{\theta}_n - \theta}{\sigma/\sqrt{n}} \xrightarrow{d} N(0, 1) \text{ as } n \rightarrow \infty$$

where $\hat{\theta}_n = \sum_{i=1}^n Y_i/n$, $\theta := \mathbb{E}[Y_i]$ and $\sigma^2 := \text{Var}(Y_i)$. \square

Note that we assume nothing about the distribution of the Y_i 's other than that $\mathbb{E}[Y_i^2] < \infty$. If n is sufficiently large in our simulations, then we can use the CLT to construct confidence intervals for $\theta := \mathbb{E}[Y]$. We now describe how to do this.

1.2 An Approximate $100(1 - \alpha)\%$ Confidence Interval for θ

Let $z_{1-\alpha/2}$ be the the $(1 - \alpha/2)$ percentile point of the $N(0, 1)$ distribution so that

$$\mathbf{P}(-z_{1-\alpha/2} \leq Z \leq z_{1-\alpha/2}) = 1 - \alpha$$

when $Z \sim N(0, 1)$. Suppose now that we have simulated IID samples, Y_i , for $i = 1, \dots, n$, and that we want to construct a $100(1 - \alpha)\%$ CI for $\theta = \mathbb{E}[Y]$. That is, we want $L(\mathbf{Y})$ and $U(\mathbf{Y})$ such that

$$\mathbf{P}(L(\mathbf{Y}) \leq \theta \leq U(\mathbf{Y})) = 1 - \alpha.$$

The CLT implies $\sqrt{n}(\hat{\theta}_n - \theta)/\sigma$ is approximately $N(0, 1)$ for large n so we have

$$\begin{aligned} \mathbf{P}\left(-z_{1-\alpha/2} \leq \frac{\sqrt{n}(\hat{\theta}_n - \theta)}{\sigma} \leq z_{1-\alpha/2}\right) &\approx 1 - \alpha \\ \Rightarrow \mathbf{P}\left(-z_{1-\alpha/2} \frac{\sigma}{\sqrt{n}} \leq \hat{\theta}_n - \theta \leq z_{1-\alpha/2} \frac{\sigma}{\sqrt{n}}\right) &\approx 1 - \alpha \\ \Rightarrow \mathbf{P}\left(\hat{\theta}_n - z_{1-\alpha/2} \frac{\sigma}{\sqrt{n}} \leq \theta \leq \hat{\theta}_n + z_{1-\alpha/2} \frac{\sigma}{\sqrt{n}}\right) &\approx 1 - \alpha. \end{aligned}$$

Our approximate $100(1 - \alpha)\%$ CI for θ is therefore given by

$$[L(\mathbf{Y}), U(\mathbf{Y})] = \left[\hat{\theta}_n - z_{1-\alpha/2} \frac{\sigma}{\sqrt{n}}, \hat{\theta}_n + z_{1-\alpha/2} \frac{\sigma}{\sqrt{n}} \right]. \quad (2)$$

Recall that $\hat{\theta}_n = (Y_1 + \dots + Y_n)/n$, so L and U are indeed functions of \mathbf{Y} . There is still a problem, however, as we do not usually know σ^2 . We resolve this issue by estimating σ^2 with

$$\hat{\sigma}_n^2 = \frac{\sum_{i=1}^n (Y_i - \hat{\theta}_n)^2}{n - 1}.$$

It is easy to show that $\hat{\sigma}_n^2$ is an unbiased estimator of σ^2 and that $\hat{\sigma}_n^2 \rightarrow \sigma^2$ w.p. 1 as $n \rightarrow \infty$. So now we replace σ with $\hat{\sigma}_n$ in (2) to obtain

$$[L(\mathbf{Y}), U(\mathbf{Y})] = \left[\hat{\theta}_n - z_{1-\alpha/2} \frac{\hat{\sigma}_n}{\sqrt{n}}, \hat{\theta}_n + z_{1-\alpha/2} \frac{\hat{\sigma}_n}{\sqrt{n}} \right] \quad (3)$$

as our *approximate* $100(1 - \alpha)\%$ CI for θ when n is large.

Remark 1 Note that when we obtain sample values of $\mathbf{y} = (y_1, \dots, y_n)$, then $[L(\mathbf{y}), U(\mathbf{y})]$ becomes a real interval. Then we can no longer say (why not?) that

$$\mathbf{P}(\theta \in [L(\mathbf{y}), U(\mathbf{y})]) = 1 - \alpha.$$

Instead, we say that we are $100(1 - \alpha)\%$ confident that $[L(\mathbf{y}), U(\mathbf{y})]$ contains θ . Furthermore, the smaller the value of $U(\mathbf{y}) - L(\mathbf{y})$, the more confidence we will have in our estimate of θ .

Example 1 (Pricing a European Call Option)

Suppose we want to estimate the price, C_0 , of a call option on a stock whose price process, S_t , is a $GBM(\mu, \sigma)$. The relevant parameters are $r = .05$, $T = 0.5$ years, $S_0 = \$100$, $\sigma = 0.2$ and strike $K = \$110$. Then we know that

$$C_0 = \mathbb{E}_0^Q[e^{-rT} \max(S_T - K, 0)]$$

where we can assume that $S_t \sim GBM(r, \sigma)$ under the risk-neutral probability measure, Q . That is, we assume $S_T = S_0 \exp((r - \sigma^2/2)T + \sigma Z)$ where $Z \sim N(0, T)$. Though we can of course compute C_0 exactly, we can also estimate C_0 using Monte Carlo with (3) yielding an approximate $100(1 - \alpha)\%$ CI for C_0 with $Y_i := e^{-rT} \max(S_T^{(i)} - K, 0)$ denoting the i^{th} discounted sample payoff of the option. Based on $n = 100k$ samples, we obtain $[15.16, 15.32]$ as our approximate 95% CI for C_0 . ■

Properties of the Confidence Interval

The *width* of the confidence interval is given by

$$U - L = \frac{2\hat{\sigma}_n z_{1-\alpha/2}}{\sqrt{n}}$$

and so the *half-width* then is $(U - L)/2$. The width clearly depends on α , $\hat{\sigma}_n$ and n . However, $\hat{\sigma}_n \rightarrow \sigma$ almost surely as $n \rightarrow \infty$, and σ is a constant. Therefore, for a fixed α , we need to increase n if we are to decrease the width of the confidence interval. Indeed, since $U - L \propto \frac{1}{\sqrt{n}}$, we can see for example that we would need to increase n by a factor of four in order to decrease the width of the confidence interval by only a factor of two.

2 Run-Length Control

Up to this point we have selected n in advance and then computed the approximate CI. The width of the CI is then a measure of the error in our estimator. Now we will do the reverse by first choosing some error criterion that we want our estimator to satisfy, and then choosing n so that this criterion is satisfied.

There are two types of error that we will consider:

1. Absolute error, which is given by $E_a := |\hat{\theta}_n - \theta|$ and
2. Relative error, which is given by $E_r := \left| \frac{\hat{\theta}_n - \theta}{\theta} \right|$.

Now we know that $\hat{\theta}_n \rightarrow \theta$ w.p. 1 as $n \rightarrow \infty$ so that E_a and E_r both $\rightarrow 0$ as $n \rightarrow \infty$. (If $\theta = 0$ then E_r is not defined.) However, in practice $n \neq \infty$ and so the errors will be non-zero. We specify the following error criterion:

Error Criterion: Given $0 \leq \alpha \leq 1$ and $\epsilon \geq 0$, we want $\mathbf{P}(E \leq \epsilon) = 1 - \alpha$. E is the error type we have specified, i.e., relative or absolute.

The goal then is to choose n so that the error criterion is approximately satisfied and this is easily done. Suppose, for example, that we want to control absolute error, E_a . Then, as we saw earlier,

$$\mathbf{P}\left(\hat{\theta}_n - z_{1-\alpha/2} \frac{\sigma}{\sqrt{n}} \leq \theta \leq \hat{\theta}_n + z_{1-\alpha/2} \frac{\sigma}{\sqrt{n}}\right) \approx 1 - \alpha.$$

This then implies $\mathbf{P}\left(|\hat{\theta}_n - \theta| \leq z_{1-\alpha/2} \frac{\sigma}{\sqrt{n}}\right) \approx 1 - \alpha$, so in terms of E_a we have

$$\mathbf{P}\left(E_a \leq z_{1-\alpha/2} \frac{\sigma}{\sqrt{n}}\right) \approx 1 - \alpha.$$

If we then want $\mathbf{P}(E_a \leq \epsilon) \approx 1 - \alpha$, it clearly suffices to choose n such that

$$n = \frac{\sigma^2 z_{1-\alpha/2}^2}{\epsilon^2}.$$

If we are working with relative error, then a similar argument implies that $\mathbf{P}(E_r \leq \epsilon) \approx 1 - \alpha$ if

$$n = \frac{\sigma^2 z_{1-\alpha/2}^2}{\theta^2 \epsilon^2}.$$

There are still some problems, however:

1. When we are controlling E_r , we need to know σ and θ in advance.
2. When we are controlling E_a , we need to know σ in advance.

Of course we do not usually know σ or θ in advance. In fact, θ is what we are trying to estimate! There are two methods we can use to overcome this problem: the *two-stage method* and the *sequential method*, both of which we will now describe.

2.1 The Two-Stage Procedure

Suppose we want to satisfy the condition $\mathbf{P}(E_a \leq \epsilon) = 1 - \alpha$ so that we are trying to control the absolute error. Then we saw earlier that we would like to set

$$n = \frac{\sigma^2 z_{1-\alpha/2}^2}{\epsilon^2}.$$

Unfortunately, we don't know σ^2 but we can solve this problem by first doing a *pilot* simulation to estimate it. The idea is to do a small number, p , of initial runs to estimate σ^2 . We then use our estimate, $\hat{\sigma}^2$, to compute an estimate, \hat{n} , of n . Finally, we repeat the simulation, but now we use \hat{n} runs. We have the following algorithm.

Two-Stage Monte Carlo Simulation for Estimating $\mathbb{E}[h(\mathbf{X})]$

```

/* Do pilot simulation first */
for i = 1 to p
    generate  $\mathbf{X}^i$ 
end for
set  $\hat{\theta} = \sum h(\mathbf{X}^i)/p$ 
set  $\hat{\sigma}^2 = \sum (h(\mathbf{X}^i) - \hat{\theta})^2 / (p - 1)$ 
set  $n = \frac{\hat{\sigma}^2 z_{1-\alpha/2}^2}{\epsilon^2}$ 

/* Now do main simulation */
for i = 1 to n
    generate  $\mathbf{X}^i$ 
end for
set  $\hat{\theta}_n = \sum h(\mathbf{X}^i)/n$ 
set  $\hat{\sigma}_n^2 = \sum (h(\mathbf{X}^i) - \hat{\theta}_n)^2 / (n - 1)$ 
set 100(1 -  $\alpha$ ) % CI =  $\left[ \hat{\theta}_n - z_{1-\alpha/2} \frac{\hat{\sigma}_n}{\sqrt{n}}, \hat{\theta}_n + z_{1-\alpha/2} \frac{\hat{\sigma}_n}{\sqrt{n}} \right]$ 

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For this method to work, it is important that $\hat{\theta}$ and $\hat{\sigma}^2$ be sufficiently good estimates of θ and σ^2 . Therefore, it is important to make p sufficiently large. In practice, we usually take $p \geq 50$. We can use an analogous two-stage procedure if we want to control the *relative* error and have $\mathbf{P}(E_r \leq \epsilon) = 1 - \alpha$.

2.2 The Sequential Procedure

Suppose again that we wish to satisfy the condition $\mathbf{P}(E_a \leq \epsilon) = 1 - \alpha$. Then we saw earlier that we would like to set

$$n = \frac{\sigma^2 z_{1-\alpha/2}^2}{\epsilon^2}.$$

In contrast to the pilot procedure, we do not precompute n during the sequential procedure. Instead, we continue to generate samples until

$$\frac{\hat{\sigma}_n z_{1-\alpha/2}}{\sqrt{n}} \leq \epsilon$$

where $\hat{\sigma}_n$ is again the estimate of σ based upon the first n samples. It is important that n be sufficiently large so that $\hat{\theta}_n$ and $\hat{\sigma}_n^2$ are sufficiently good estimates of θ and σ^2 , respectively. As a result, we typically insist that $n \geq 50$ before we stop. Approximate confidence intervals are then computed as usual.

Question: Have we allowed any biases to creep in here?

We have the following algorithm:

Sequential Monte Carlo Simulation for Estimating $\mathbb{E}[h(\mathbf{X})]$

```

set check = 0, n = 1
while (check = 0)
  generate  $\mathbf{X}^n$ 
  set  $\hat{\theta}_n = \sum h(\mathbf{X}^i)/n$ 
  set  $\hat{\sigma}_n^2 = \sum (h(\mathbf{X}^i) - \hat{\theta}_n)^2 / (n - 1)$ 
  if ( $n \geq p$ ) and  $\left( \frac{\hat{\sigma}_n z_{1-\alpha/2}}{\sqrt{n}} \leq \epsilon \right)$ 
    check = 1
  else
    n = n + 1
  end if
end while
set 100(1 -  $\alpha$ ) % CI =  $\left[ \hat{\theta}_n - z_{1-\alpha/2} \frac{\hat{\sigma}_n}{\sqrt{n}}, \hat{\theta}_n + z_{1-\alpha/2} \frac{\hat{\sigma}_n}{\sqrt{n}} \right]$ 

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In practice we do **not** need to store every value, $h(\mathbf{X}^i)$ for $i = 1, \dots, n$, in order to update $\hat{\theta}_n$ and $\hat{\sigma}_n$. Indeed, we can update $\hat{\theta}_n$ and $\hat{\sigma}_n$ efficiently by observing that

$$\hat{\theta}_n = \hat{\theta}_{n-1} + \frac{h(\mathbf{X}^n) - \hat{\theta}_{n-1}}{n} \quad \text{and}$$

$$\hat{\sigma}_n^2 = \left(\frac{n-2}{n-1} \right) \hat{\sigma}_{n-1}^2 + n \left(\hat{\theta}_n - \hat{\theta}_{n-1} \right)^2.$$

If we want to control the *relative* error and have $\mathbf{P}(E_r \leq \epsilon) = 1 - \alpha$, then we would simulate samples until

$$\frac{\hat{\sigma}_n (z_{1-\alpha/2})}{\hat{\theta}_n \sqrt{n}} \leq \epsilon.$$

3 Output Analysis Using the Bootstrap

We can view¹ our output analysis problem as one of estimating

$$\text{MSE}(F) := \mathbb{E}_F \left[(g(Y_1, \dots, Y_n) - \theta(F))^2 \right] \quad (4)$$

where $\theta(F) = \mathbb{E}_F[X]$, $g(Y_1, \dots, Y_n) := \bar{Y}$ and F denotes the CDF of Y . In that case, we saw in Section 1 how we could use the CLT to construct approximate confidence intervals for θ . While this is certainly the most common context in which we encounter (4), other situations arise where the CLT cannot be easily used to obtain a confidence interval for $\theta(F)$. For example, if $\theta(F) = \text{Var}(Y)$ or $\theta(F) = \mathbb{E}[Y | Y \geq \alpha]$, then an alternative method of constructing a confidence interval for θ will be required. The bootstrap method provides such an alternative and in order to describe the method we will assume our problem is to estimate $\text{MSE}(F)$ as in (4).

To begin with, recall that the empirical distribution, F_e , is defined to be the CDF of the distribution that places a weight of $1/n$ on each of the simulated values Y_1, \dots, Y_n . The empirical CDF therefore satisfies

$$F_e(y) = \frac{\sum_{i=1}^n \mathbf{1}_{\{Y_i \leq y\}}}{n}$$

and for large n it can be shown (and should be intuitively clear) that F_e should be² a good approximation to F . Therefore, as long as θ is sufficiently well-behaved, i.e. a “continuous” function of F , then for sufficiently large n we should have

$$\text{MSE}(F) \approx \text{MSE}(F_e) = \mathbb{E}_{F_e} \left[(g(Y_1, \dots, Y_n) - \theta(F_e))^2 \right]. \quad (5)$$

The quantity $\text{MSE}(F_e)$ is known as the *bootstrap approximation* to $\text{MSE}(F)$ and is easy to estimate via simulation as we shall see below. But first, however, we will consider an example where $\text{MSE}(F_e)$ can be computed exactly. Indeed the bootstrap is not required in this case but it is nonetheless instructive to see the calculations written out explicitly.

Example 2 (Applying the Bootstrap to the Sample Mean)

Suppose we wish to estimate $\theta(F) = \mathbb{E}_F[Y]$ via the estimator $\hat{\theta} = g(Y_1, \dots, Y_n) := \bar{Y}$. As noted above, the bootstrap is not necessary in this case as we can apply the CLT directly as in Section 1 to obtain confidence intervals for $\hat{\theta}$ or equivalently, we can estimate the mean-squared error $\mathbb{E} \left[(\bar{Y} - \theta)^2 \right] = \sigma^2/n$ with $\hat{\sigma}_n^2/n = \sum_{i=1}^n (y_i - \bar{y})^2 / (n(n-1))$.

Letting \bar{y} denote the mean of the observed, i.e. simulated, data-points y_1, \dots, y_n , we obtain that the bootstrap estimator is given by

$$\begin{aligned} \text{MSE}(F_e) &= \mathbb{E}_{F_e} \left[\left(\frac{\sum_{i=1}^n Y_i}{n} - \bar{y} \right)^2 \right] \\ &= \text{Var}_{F_e} \left(\frac{\sum_{i=1}^n Y_i}{n} \right) \end{aligned} \quad (6)$$

$$\begin{aligned} &= \frac{\text{Var}_{F_e}(Y)}{n} \\ &= \frac{\sum_{i=1}^n (y_i - \bar{y})^2}{n^2} \end{aligned} \quad (7)$$

where (6) follows since $\mathbb{E}_{F_e}[Y] = \bar{y}$, and (7) follows since the Y_i 's are IID F_e . We therefore see that the bootstrap approximation to the MSE is almost identical to our usual estimator, $\hat{\sigma}_n^2/n$. ■

¹We follow Sheldon M. Ross's *Simulation* in our development of the bootstrap here.

²Indeed it can be shown that $F_e(y)$ converges to $F(y)$ uniformly in y w.p. 1 as $n \rightarrow \infty$.

In contrast to Example 2, we cannot usually compute $\text{MSE}(F_e)$ explicitly, but as it's an expectation we can easily use Monte-Carlo to estimate it. In this case we need to simulate from F_e which is easy to do and so we obtain the following bootstrap algorithm for estimating $\text{MSE}(F)$.

Bootstrap Simulation Algorithm for Estimating $\text{MSE}(F)$

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for  $i = 1$  to  $B$ 
    generate  $Y_1, \dots, Y_n$  IID from  $F_e$ 
    set  $\hat{\theta}_i^b = g(Y_1, \dots, Y_n)$ 
    set  $Z_i^b = [\hat{\theta}_i^b - \theta(F_e)]^2$ 
end for
set  $\widehat{\text{MSE}}(F) = \sum_{b=1}^B Z^{(b)} / B$ 

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The Z_i^b 's (or equivalently the $\hat{\theta}_i^b$'s) are the bootstrap samples and a value of $B = 100$ is often sufficient to obtain a sufficiently accurate estimate. In the next example we apply the bootstrap approach in a *historical* simulation context where we have real data observations as opposed to simulated data. (The disadvantage with historical simulation is that we typically have no control over n .)

Example 3 (Estimating the Minimum Variance Portfolio)

Suppose we wish to invest a fixed sum of money in two financial assets, X and Z say, that yield random returns of R_x and R_z , respectively. We invest a fraction θ of our wealth in X , and the remaining $1 - \theta$ in Z . The goal is to choose θ to minimize the total variance, $\text{Var}(\theta R_x + (1 - \theta)R_z)$, of our investment return. It is easy to see that the minimizing θ is given by

$$\theta = \frac{\sigma_z^2 - \sigma_{xz}}{\sigma_x^2 + \sigma_z^2 - 2\sigma_{xz}} \quad (8)$$

where $\sigma_x^2 = \text{Var}(R_x)$, $\sigma_z^2 = \text{Var}(R_z)$ and $\sigma_{xz} = \text{Cov}(R_x, R_z)$. In practice, we do not know these quantities and therefore have to estimate them from historical data. We therefore obtain

$$\hat{\theta} = \frac{\hat{\sigma}_z^2 - \hat{\sigma}_{xz}}{\hat{\sigma}_x^2 + \hat{\sigma}_z^2 - 2\hat{\sigma}_{xz}}. \quad (9)$$

as our estimator of the minimum variance portfolio with $\hat{\sigma}_x^2$, $\hat{\sigma}_z^2$ and $\hat{\sigma}_{xz}$ estimated from historical return data Y_1, \dots, Y_n with $Y_i := (R_x^{(i)}, R_z^{(i)})$ the joint return in period i .

We would like to know how good an estimator $\hat{\theta}$ is. More specifically, what is the (mean-squared) error when we use $\hat{\theta}$? We can answer this question using the bootstrap with $\theta(F) := \theta$ and $g(Y_1, \dots, Y_n) = \hat{\theta}$ the estimator given by (9). ■

Exercise 2 Provide pseudo-code for estimating $\text{MSE}(\hat{\theta}) := \text{MSE}(F)$, in Example 3.

Exercise 3 Consider the problem of estimating $\theta(F) = \mathbb{E}[Y | Y \geq \beta]$ for some fixed constant, β . Explain how you would use the bootstrap to estimate $\text{MSE}(F)$ in this case given n Monte-Carlo samples Y_1, \dots, Y_n .

3.1 Constructing Bootstrap Confidence Intervals

The bootstrap method is also widely used to construct confidence intervals and here we will consider the so-called *basic bootstrap interval*. Consider our bootstrap samples $\hat{\theta}_1^b, \dots, \hat{\theta}_B^b$ and suppose we want a $1 - \alpha$ confidence interval for $\theta = \theta(F)$. Let q_l and q_u be the $\alpha/2$ lower- and upper-sample quantiles, respectively, of the bootstrap samples. Then the fraction of bootstrap samples satisfying

$$q_l \leq \hat{\theta}^b \leq q_u \quad (10)$$

is $1 - \alpha$. But (10) is equivalent to

$$\hat{\theta} - q_u \leq \hat{\theta} - \hat{\theta}^b \leq \hat{\theta} - q_l \quad (11)$$

where $\hat{\theta} = g(y_1, \dots, y_n)$ is our estimate of θ computed using the original data-set. This implies $\hat{\theta} - q_u$ and $\hat{\theta} - q_l$ are the lower and upper quantiles for $\hat{\theta} - \hat{\theta}^b$. The basic bootstrap assumes they are also the quantiles for $\theta - \hat{\theta}$. This makes sense intuitively – and can be justified mathematically as $n \rightarrow \infty$ and if θ is a “continuous” function of F . It therefore follows that

$$\hat{\theta} - q_u \leq \theta - \hat{\theta} \leq \hat{\theta} - q_l \quad (12)$$

will occur in approximately in a fraction $1 - \alpha$ of samples. Adding $\hat{\theta}$ across (12) yields an approximate $(1 - \alpha)\%$ CI for θ of

$$(\hat{\theta} - q_u, \hat{\theta} - q_l).$$