Machine Learning for OR & FE The EM Algorithm

Martin Haugh

Department of Industrial Engineering and Operations Research Columbia University Email: martin.b.haugh@gmail.com The EM Algorithm E.G. Missing Data in a Multinomial Model E.G. Normal Mixture Models Revisited

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The EM Algorithm (for Computing ML Estimates)

Assume the complete data-set consists of $\mathcal{Z} = (\mathcal{X}, \mathcal{Y})$

– but only \mathcal{X} is observed.

The complete-data log likelihood is denoted by $l(\theta; \mathcal{X}, \mathcal{Y})$ where θ is the unknown parameter vector for which we wish to find the MLE.

E-Step: Compute the expected value of $l(\theta; \mathcal{X}, \mathcal{Y})$ given the observed data, \mathcal{X} , and the current parameter estimate θ_{old} . In particular, we define

$$Q(\theta; \theta_{old}) := \mathsf{E} \left[l(\theta; \mathcal{X}, \mathcal{Y}) \mid \mathcal{X}, \theta_{old} \right] \\ = \int l(\theta; \mathcal{X}, y) \ p(y \mid \mathcal{X}, \theta_{old}) \ dy$$
(1)

$$\begin{split} &-p(\cdot \mid \mathcal{X}, \theta_{old}) \equiv \text{conditional density of } \mathcal{Y} \text{ given observed data, } \mathcal{X}, \text{ and } \theta_{old} \\ &-Q(\theta; \theta_{old}) \text{ is the expected complete-data log-likelihood.} \end{split}$$

M-Step: Compute $\theta_{new} := \max_{\theta} Q(\theta; \theta_{old})$.

The EM Algorithm

Now set $\theta_{old}=\theta_{new}$ and iterate E- and M-steps until sequence of θ_{new} 's converges.

Convergence to a local maximum can be guaranteed under very general conditions

- will see why below.

If suspected that log-likelihood function has multiple local maximums then the EM algorithm should be run many times

– using a different starting value of θ_{old} on each occasion.

The ML estimate of θ is then taken to be the best of the set of local maximums obtained from the various runs of the EM algorithm.

Why Does the EM Algorithm Work?

Will use $p(\cdot \mid \cdot)$ to denote a generic conditional PDF. Now observe that

$$\begin{split} l(\theta; \mathcal{X}) &= \ln p(\mathcal{X} \mid \theta) \\ &= \ln \int p(\mathcal{X}, y \mid \theta) \, dy \\ &= \ln \int \frac{p(\mathcal{X}, y \mid \theta)}{p(y \mid \mathcal{X}, \theta_{old})} p(y \mid \mathcal{X}, \theta_{old}) \, dy \\ &= \ln \mathsf{E} \left[\frac{p(\mathcal{X}, \mathcal{Y} \mid \theta)}{p(\mathcal{Y} \mid \mathcal{X}, \theta_{old})} \mid \mathcal{X}, \theta_{old} \right] \\ &\geq \mathsf{E} \left[\ln \left(\frac{p(\mathcal{X}, \mathcal{Y} \mid \theta)}{p(\mathcal{Y} \mid \mathcal{X}, \theta_{old})} \right) \mid \mathcal{X}, \theta_{old} \right] \quad \text{by Jensen's inequality} \quad (2) \\ &= \mathsf{E} \left[\ln p(\mathcal{X}, \mathcal{Y} \mid \theta) \mid \mathcal{X}, \theta_{old} \right] - \mathsf{E} \left[\ln p(\mathcal{Y} \mid \mathcal{X}, \theta_{old}) \mid \mathcal{X}, \theta_{old} \right] \\ &= Q(\theta; \theta_{old}) - \mathsf{E} \left[\ln p(\mathcal{Y} \mid \mathcal{X}, \theta_{old}) \mid \mathcal{X}, \theta_{old} \right] \quad (3) \end{split}$$

Also clear (why?) that inequality in (2) is an equality if we take $\theta = \theta_{old}$.

Why Does the EM Algorithm Work?

Let $g(\theta \mid \theta_{old})$ denote the right-hand-side of (3).

Therefore have

$$l(\theta; \mathcal{X}) \geq g(\theta \mid \theta_{old})$$

for all θ with equality when $\theta = \theta_{old}$.

So any value of θ that increases $g(\theta \mid \theta_{old})$ beyond $g(\theta_{old} \mid \theta_{old})$ must also increase $l(\theta; \mathcal{X})$ beyond $l(\theta_{old}; \mathcal{X})$.

The M-step finds such a θ by maximizing $Q(\theta; \theta_{old})$ over θ

- this is equivalent (why?) to maximizing $g(\theta \mid \theta_{old})$ over θ .

Also worth noting that in many applications the function $Q(\theta;\theta_{old})$ will be a convex function of θ

- and therefore easy to optimize.

Schematic for general E-M algorithm



Figure 9.14 from Bishop (where $\mathcal{L}(q, \theta)$ is $g(\theta \mid \theta_{old})$ in our notation)

Suppose $\mathbf{x} := (x_1, x_2, x_3, x_4)$ is a sample from a $\mathsf{Mult}(n, \pi_{\theta})$ distribution where

$$\pi_{\theta} = \left(\frac{1}{2} + \frac{1}{4}\theta, \frac{1}{4}(1-\theta), \frac{1}{4}(1-\theta), \frac{1}{4}\theta\right).$$

The likelihood, $L(\theta; \mathbf{x})$, is then given by

$$L(\theta; \mathbf{x}) = \frac{n!}{x_1! x_2! x_3! x_4!} \left(\frac{1}{2} + \frac{1}{4}\theta\right)^{x_1} \left(\frac{1}{4}(1-\theta)\right)^{x_2} \left(\frac{1}{4}(1-\theta)\right)^{x_3} \left(\frac{1}{4}\theta\right)^{x_4}$$

so that the log-likelihood $l(\boldsymbol{\theta};\mathbf{x})$ is

$$l(\theta; \mathbf{x}) = C + x_1 \ln\left(\frac{1}{2} + \frac{1}{4}\theta\right) + (x_2 + x_3) \ln(1 - \theta) + x_4 \ln(\theta)$$

- where C is a constant that does not depend on θ .

Could try to maximize $l(\theta; \mathbf{x})$ over θ directly using standard non-linear optimization algorithms

- but we will use the EM algorithm instead.

To do this we assume the complete data is given by $\mathbf{y} := (y_1, y_2, y_3, y_4, y_5)$ and that \mathbf{y} has a $\mathsf{Mult}(n, \pi_{\theta}^*)$ distribution where

$$\pi_{\theta}^{*} = \left(\frac{1}{2}, \frac{1}{4}\theta, \frac{1}{4}(1-\theta), \frac{1}{4}(1-\theta), \frac{1}{4}\theta\right).$$

However, instead of observing y we only observe $(y_1 + y_2, y_3, y_4, y_5)$, i.e, x.

Therefore take $\mathcal{X} = (y_1 + y_2, y_3, y_4, y_5)$ and take $\mathcal{Y} = y_2$.

Log-likelihood of complete data then given by

 $l(\theta; \mathcal{X}, \mathcal{Y}) = C + y_2 \ln(\theta) + (y_3 + y_4) \ln(1 - \theta) + y_5 \ln(\theta)$

where again C is a constant containing all terms that do not depend on θ .

Also "clear" that conditional "density" of ${\mathcal Y}$ satisfies

$$f(\mathcal{Y} \mid \mathcal{X}, \theta) = \operatorname{Bin}\left(y_1 + y_2, \frac{\theta/4}{1/2 + \theta/4}
ight).$$

Can now implement the E-step and M-step.

Recall that $Q(\theta; \theta_{old}) := \mathsf{E}\left[l(\theta; \mathcal{X}, \mathcal{Y}) \mid \mathcal{X}, \theta_{old}\right].$

E-Step: Therefore have

$$\begin{array}{lll} Q(\theta;\theta_{old}) & := & C \,+\, \mathsf{E} \left[y_2 \ln \left(\theta \right) \,\mid \mathcal{X}, \theta_{old} \right] \,+\, (y_3 + y_4) \ln \left(1 - \theta \right) \,+\, y_5 \ln \left(\theta \right) \\ & = & C \,+\, (y_1 + y_2) p_{old} \ln \left(\theta \right) \,+\, (y_3 + y_4) \ln \left(1 - \theta \right) \,+\, y_5 \ln \left(\theta \right) \end{array}$$

where

$$p_{old} := \frac{\theta_{old}/4}{1/2 + \theta_{old}/4}.$$
(4)

M-Step: Must now maximize $Q(\theta; \theta_{old})$ to find θ_{new} .

Taking the derivative we obtain

$$\begin{array}{rcl} \frac{dQ}{d\theta} & = & \frac{(y_1 + y_2)}{\theta} p_{old} - \frac{(y_3 + y_4)}{1 - \theta} + \frac{y_5}{\theta} \\ & = & 0 \quad \text{when } \theta \ = \ \theta_{new} \end{array}$$

where

$$heta_{new} := rac{y_5 + p_{old}(y_1 + y_2)}{y_3 + y_4 + y_5 + p_{old}(y_1 + y_2)}.$$

Equations (4) and (5) now define the EM iteration

– which begins with some judiciously chosen value of θ_{old} .

(5)

E.G. Normal Mixture Models Revisited

Clustering via normal mixture models is an example of probabilistic clustering

- we assume the data are IID draws
- will consider only the scalar case but note the vector case is similar.

So suppose $\mathcal{X} = (X_1, \dots, X_n)$ are IID random variables each with PDF

$$f_x(x) = \sum_{j=1}^m p_j \; rac{e^{-(x-\mu_j)^2/2\sigma_j^2}}{\sqrt{2\pi\sigma_j^2}}$$

where $p_j \geq 0$ for all j and where $\sum_j p_j = 1$

- parameters are the p_j 's, μ_j 's and σ_j 's
- typically estimated via MLE
- which we can do via the EM algorithm.

Normal Mixture Models Revisited

We assume the presence of an additional or latent random variable, Y, where

$$P(Y = j) = p_j, \quad j = 1, ..., m.$$

Realized value of $\,Y$ then determines which of the $\,m$ normals generates the corresponding value of $\,X$

- so there are n such random variables, $(Y_1, \ldots, Y_n) := \mathcal{Y}$.

Note that

$$f_{x|y}(x_i \mid y_i = j, \theta) = \frac{1}{\sqrt{2\pi\sigma_j^2}} e^{-(x_i - \mu_j)^2 / 2\sigma_j^2}$$
(6)

where $\theta := (p_1, \ldots, p_m, \mu_1, \ldots, \mu_m, \sigma_1, \ldots, \sigma_m)$ is the unknown parameter vector.

The complete data likelihood is given by

$$L(\theta; \mathcal{X}, \mathcal{Y}) = \prod_{i=1}^{n} p_{y_i} \frac{1}{\sqrt{2\pi\sigma_{y_i}^2}} e^{-(x_i - \mu_{y_i})^2 / 2\sigma_{y_i}^2}.$$

Normal Mixture Models

The EM algorithm starts with an initial guess, θ_{old} , and then iterates the E-step and M-step until convergence.

E-Step: Need to compute $Q(\theta; \theta_{old}) := \mathsf{E}[l(\theta; \mathcal{X}, \mathcal{Y}) \mid \mathcal{X}, \theta_{old}].$

Straightforward to show that

$$Q(\theta; \theta_{old}) = \sum_{i=1}^{n} \sum_{j=1}^{m} P(Y_i = j \mid x_i, \theta_{old}) \ln \left(f_{x|y}(x_i \mid y_i = j, \theta) P(Y_i = j \mid \theta) \right).$$
(7)

Note that $f_{x|y}(x_i \mid y_i = j, \theta)$ is given by (6) and that $P(Y_i = j \mid \theta_{old}) = p_{j,old}$.

Finally, can compute (7) analytically since

$$P(Y_{i} = j \mid x_{i}, \theta_{old}) = \frac{P(Y_{i} = j, X_{i} = x_{i} \mid \theta_{old})}{P(X_{i} = x_{i} \mid \theta_{old})}$$

= $\frac{f_{x|y}(x_{i} \mid y_{i} = j, \theta_{old}) P(Y_{i} = j \mid \theta_{old})}{\sum_{k=1}^{m} f_{x|y}(x_{i} \mid y_{i} = k, \theta_{old}) P(Y_{i} = k \mid \theta_{old})}.$ (8)

Normal Mixture Models

M-Step: Can now maximize $Q(\theta; \theta_{old})$ by setting the vector of partial derivatives, $\partial Q/\partial \theta$, equal to 0 and solving for θ_{new} .

After some algebra, we obtain

$$\mu_{j,new} = \frac{\sum_{i=1}^{n} x_i P(Y_i = j \mid x_i, \theta_{old})}{\sum_{i=1}^{n} P(Y_i = j \mid x_i, \theta_{old})}$$
(9)

$$\sigma_{j,new}^2 = \frac{\sum_{i=1}^{n} (x_i - \mu_j)^2 P(Y_i = j \mid x_i, \theta_{old})}{\sum_{i=1}^{n} P(Y_i = j \mid x_i, \theta_{old})}$$
(10)

$$p_{j,new} = \frac{1}{n} \sum_{i=1}^{n} P(Y_i = j \mid x_i, \theta_{old}).$$
(11)

Given an initial estimate, θ_{old} , the EM algorithm cycles through (9) to (11) repeatedly, setting $\theta_{old} = \theta_{new}$ after each cycle, until the estimates converge.

Kullback-Leibler Divergence

Let P and Q be two probability distributions such that if $Q(\mathbf{x})=0$ then $P(\mathbf{x})=0.$

The Kullback-Leibler (KL) divergence or relative entropy of Q from P is defined to be

$$\mathsf{KL}(P \mid\mid Q) = \int_{\mathbf{x}} P(\mathbf{x}) \ln\left(\frac{P(\mathbf{x})}{Q(\mathbf{x})}\right)$$
(12)

with the understanding that $0 \log 0 = 0$.

The KL divergence is a fundamental concept in information theory and machine learning.

Can imagine ${\cal P}$ representing some true but unknown distribution that we approximate with ${\cal Q}$

– $KL(P \parallel Q)$ then measures the "distance" between P and Q.

This interpretation is valid because we will see below that $KL(P \mid\mid Q) \ge 0$

- with equality if and only if P = Q.

Kullback-Leibler Divergence

The KL divergence is not a true measure of distance since it is:

- 1. Asymmetric in that $\mathsf{KL}(P \mid\mid Q) \neq \mathsf{KL}(Q \mid\mid P)$
- 2. And does not satisfy the triangle inequality.

In order to see that ${\rm KL}(P \mid\mid Q) \geq 0$ we first recall that a function $f(\cdot)$ is convex on $\mathbb R$ if

$$f(\alpha x + (1 - \alpha)y) \le \alpha f(x) + (1 - \alpha)f(y) \quad \text{for all } \alpha \in [0, 1].$$

We also recall Jensen's inequality:

Jensen's Inequality: Let $f(\cdot)$ be a convex function on \mathbb{R} and suppose $\mathsf{E}[X] < \infty$ and $\mathsf{E}[f(X)] < \infty$. Then $f(\mathsf{E}[X]) \le \mathsf{E}[f(X)]$.

Kullback-Leibler Divergence

Noting that $-\ln(x)$ is a convex function we have

$$\begin{aligned} \mathsf{KL}(P \mid\mid Q) &= -\int_{\mathbf{x}} P(\mathbf{x}) \ln\left(\frac{Q(\mathbf{x})}{P(\mathbf{x})}\right) \\ &\geq -\ln\left(\int_{\mathbf{x}} P(\mathbf{x}) \frac{Q(\mathbf{x})}{P(\mathbf{x})}\right) \end{aligned}$$
by Jensen's inequality
= 0.

Moreover it is clear from (12) that KL(P || Q) = 0 if P = Q.

In fact because $-\ln(x)$ is strictly convex it is easy to see that KL(P || Q) = 0 only if P = Q.

A Nice Optimization "Trick"

Suppose $\mathbf{c} \in \mathbb{R}^n_+$ and we wish to maximize $\sum_{i=1}^n c_i \ln(q_i)$ over pmf's, $\mathbf{q} = \{q_1, \dots, q_n\}.$ Let $\mathbf{p} = \{p_1, \dots, p_n\}$ where $p_i := c_i / \sum_j c_j$ so that \mathbf{p} is a (known) pmf. We then have:

$$\max_{\mathbf{q}} \sum_{i=1}^{n} c_{i} \ln(q_{i}) = \left(\sum_{i=1}^{n} c_{i}\right) \max_{\mathbf{q}} \left\{\sum_{i=1}^{n} p_{i} \ln(q_{i})\right\}$$
$$= \left(\sum_{i=1}^{n} c_{i}\right) \max_{\mathbf{q}} \left\{\sum_{i=1}^{n} p_{i} \ln(p_{i}) - \sum_{i=1}^{n} p_{i} \ln\left(\frac{p_{i}}{q_{i}}\right)\right\},$$
$$= \left(\sum_{i=1}^{n} c_{i}\right) \left(\sum_{i=1}^{n} p_{i} \ln(p_{i}) - \min_{\mathbf{q}} \mathsf{KL}(\mathbf{p} || \mathbf{q})\right)$$

from which it follows (why?) that the optimal q^* satisfies $q^* = p$.

Could have saved some time using this trick in earlier multinomial model example - in particular obtaining (5)

As before, goal is to maximize the likelihood function $L(\theta; \mathcal{X})$ which is given by

$$L(\theta; \mathcal{X}) = p(\mathcal{X} \mid \theta) = \int_{\mathcal{Y}} p(\mathcal{X}, y \mid \theta) \, dy.$$
(13)

Implicit assumption underlying EM algorithm: it is difficult to optimize $p(\mathcal{X} \,|\, \theta)$ with respect to θ directly

- but much easier to optimize $p(\mathcal{X}, \mathcal{Y} | \theta)$.

First introduce an arbitrary distribution, $q(\mathcal{Y})$, over the latent variables, \mathcal{Y} .

Note we can decompose log-likelihood, $l(\theta; \mathcal{X})$, into two terms according to

$$l(\theta; \mathcal{X}) := \ln p(\mathcal{X} \mid \theta) = \underbrace{\mathcal{L}(q, \theta)}_{\text{"energy"}} + \mathsf{KL}(q \mid \mid p_{\mathcal{Y} \mid \mathcal{X}})$$
(14)

 $\mathcal{L}(q,\theta)$ and $\mathsf{KL}(q\,||\, p_{\mathcal{Y}|\mathcal{X}})$ are the likelihood and KL divergence and are given by

$$\mathcal{L}(q,\theta) = \int_{\mathcal{Y}} q(\mathcal{Y}) \ln\left(\frac{p(\mathcal{X},\mathcal{Y}|\theta)}{q(\mathcal{Y})}\right)$$
(15)
$$\mathsf{KL}(q \mid\mid p_{\mathcal{Y}|\mathcal{X}}) = -\int_{\mathcal{Y}} q(\mathcal{Y}) \ln\left(\frac{p(\mathcal{Y}|\mathcal{X},\theta)}{q(\mathcal{Y})}\right).$$

It therefore follows (why?) that $\mathcal{L}(q,\theta) \leq l(\theta;\mathcal{X})$ for all distributions, $q(\cdot)$.

Can now use the decomposition of (14) to define the EM algorithm, beginning with an initial parameter estimate, θ_{old} .

E-Step: Maximize the lower bound, $\mathcal{L}(q, \theta_{old})$, with respect to $q(\cdot)$ while keeping θ_{old} fixed.

In principle this is a variational problem since we are optimizing a functional, but the solution is easily found.

First note that $l(\theta_{old}; \mathcal{X})$ does not depend on $q(\cdot)$.

Then follows from (14) with $\theta = \theta_{old}$ that maximizing $\mathcal{L}(q, \theta_{old})$ is equivalent to minimizing $\mathsf{KL}(q \mid\mid p_{\mathcal{Y}|\mathcal{X}})$.

Since this latter term is always non-negative we see that $\mathcal{L}(q,\theta_{old})$ is optimized when $\mathsf{KL}(q\,||\,p_{\mathcal{Y}|\mathcal{X}})=0$

- by earlier observation, this is the case when we take $q(\mathcal{Y}) = p(\mathcal{Y} | \mathcal{X}, \theta_{old})$.

At this point we see that the lower bound, $\mathcal{L}(q, \theta_{old})$, now equals current value of log-likelihood, $l(\theta_{old}; \mathcal{X})$.

M-Step: Keep $q(\mathcal{Y})$ fixed and maximize $\mathcal{L}(q, \theta)$ over θ to obtain θ_{new} .

This will therefore cause the lower bound to increase (if it is not already at a maximum)

- which in turn means the log-likelihood must also increase.

Moreover, at this new value θ_{new} it will no longer be the case that $\mathrm{KL}(q\,||\,p_{\mathcal{Y}|\mathcal{X}})=0$

- so by (14) the increase in the log-likelihood will be greater than the increase in the lower bound.

Comparing Classical EM With General EM

It is instructive to compare the E-step and M-step of the general EM algorithm with the corresponding steps of the original EM algorithm.

To do this, first substitute $q(\mathcal{Y}) = p(\mathcal{Y} | \mathcal{X}, \theta_{old})$ into (15) to obtain

$$\mathcal{L}(q,\theta) = Q(\theta;\theta_{old}) + \text{constant}$$
 (16)

where $Q(\theta; \theta_{old})$ is the expected complete-date log-likelihood as defined in (1).

The M-step of the general EM algorithm is therefore identical to the M-step of original algorithm since the constant term in (16) does not depend on θ .

The E-step in general EM algorithm takes $q(\mathcal{Y}) = p(\mathcal{Y} | \mathcal{X}, \theta_{old})$ which, at first glance, appears to be different to original E-step.

But there is no practical difference: original E-step simply uses $p(\mathcal{Y} | \mathcal{X}, \theta_{old})$ to compute $Q(\theta; \theta_{old})$ and, while not explicitly stated, the general E-step must also do this since it is required for the *M*-step.

E.G. Imputing Missing Data (Again)

 ${\it N}$ respondents were asked to answer ${\it m}$ questions each. The observed data are:

 $v_{iq} = \begin{cases} 1 & \text{if respondent } i \text{ answered yes to question } q \\ 0 & \text{if respondent } i \text{ answered no to question } q \\ - & \text{if respondent } i \text{ did not answer question } q \\ \begin{pmatrix} 1 & v_{iq} \in \{0, 1\} \end{cases}$

$$y_{iq} = \left\{ egin{array}{cc} 1 & v_{iq} \in \{0,1\} \ 0 & ext{otherwise} \end{array}
ight.$$

We assume the following model:

- K classes of respondents: $\pmb{\pi} = (\pi_1, \dots, \pi_K)$ with $\pi_k = \mathsf{P}(\mathsf{respondent} \ \mathsf{in} \ \mathsf{class} \ k)$
- Latent variables $z_i \in \{1, \dots, K\}$ for $i = 1, \dots, N$
- Class dependent probability of answers: $\sigma_{kq} = \mathbb{P}(v_{iq} = 1 \mid z_i = k)$
- Parameters $\theta = (\boldsymbol{\pi}, \boldsymbol{\sigma})$

Log-likelihood with $\mathcal{X} := \{v_{iq} \mid i = 1, \dots, N, q = 1, \dots, m\}$:

$$l(\theta; \mathcal{X}) = \sum_{i=1}^{N} \ln \left(\sum_{k=1}^{K} \pi_k \prod_{q: y_{iq}=1} \sigma_{kq}^{v_{iq}} (1 - \sigma_{kq})^{(1-v_{iq})} \right)$$

Question: What implicit assumptions are we making here?

EM for Imputing Missing Data

Take $\mathcal{Y} := (z_1, \ldots, z_N)$.

Complete-data log-likelihood then given by

$$l(\theta; \mathcal{X}, \mathcal{Y}) = \sum_{i=1}^{N} \sum_{k=1}^{K} \mathbb{1}_{\{z_i = k\}} \ln \left(\pi_k \prod_{q: y_{iq} = 1} \sigma_{kq}^{v_{iq}} (1 - \sigma_{kq})^{(1 - v_{iq})} \right)$$

E-Step: Need to compute $Q(\theta; \theta_{old})$. We have

$$\begin{aligned} Q(\theta;\theta_{old}) &= \mathsf{E}\left[l(\theta;\mathcal{X},\mathcal{Y}) \mid \mathcal{X},\theta_{old}\right] \\ &= \sum_{i=1}^{N} \sum_{k=1}^{K} \gamma_{ik}^{old} \ln\left(\pi_{k} \prod_{q:y_{iq}=1} \sigma_{kq}^{v_{iq}} (1-\sigma_{kq})^{(1-v_{iq})}\right) \end{aligned}$$

where

$$\begin{split} \gamma_{ik}^{old} &:= \mathsf{P}(z_i = k \mid \mathbf{v}_i, \theta_{old}) \quad \propto \quad \pi_k^{old} \mathsf{P}(\mathbf{v}_i \mid z_i = k) \\ &= \quad \pi_k^{old} \prod_{q: y_{iq} = 1} (\sigma_{kq}^{old})^{v_{iq}} (1 - \sigma_{kq}^{old})^{(1 - v_{iq})} \end{split}$$

EM for Imputing Missing Data

M-Step: Now solve for $\theta_{new} = \max_{\theta} Q(\theta; \theta_{old})$:

We have

$$Q(\theta;\theta_{old}) = \sum_{k=1}^{K} \left(\sum_{i=1}^{N} \gamma_{ik}^{old}\right) \ln(\pi_k) + \sum_{k=1}^{K} \sum_{q=1}^{m} \left(\sum_{i:y_{iq}=1} \gamma_{ik}^{old} v_{iq}\right) \ln\left(\sigma_{kq}\right) + \left(\sum_{i:y_{iq}=1} \gamma_{ik}^{old} (1-v_{iq})\right) \ln\left(1-\sigma_{kq}\right)$$

Solving $\max_{\theta} \ Q(\theta; \theta_{old})$ yields

$$\pi_k^{new} = \frac{\sum_{i=1}^N \gamma_{ik}^{old}}{\sum_{i=1}^N \sum_{j=1}^K \gamma_{ij}^{old}}$$
$$\sigma_{kq}^{new} = \frac{\sum_{i:y_{iq}=1}^N \gamma_{ik}^{old} v_{iq}}{\sum_{i:y_{iq}=1}^N \gamma_{ik}^{old}}.$$

Now iterate E- and M-steps until convergence.